# Kendall Wilkinson

## **ROBOTICS ENGINEER • SOFTWARE DEVELOPER**

#### PROFILE

Positive, enthusiastic, software developer, robotics engineer and expert problem solver with over fifteen years of experience designing, building, testing, and deploying software and hardware solutions for the Oil and Gas and Space industries.

## CONTACT

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digitalmindrobotics.com

# WORK EXPERIENCE

## Senior Software Engineer

- NOVIUM DESIGNS
- Developed space flight software to support the common birthing mechanism for a new commercial space-station using C++ and QT 6

• Created a Python application to control a tracked vehicle for mining applications implementing ROS 1 Melodic Morena in a Linux (Ubuntu 22.04) environment

- Contributed to an actuator dyno using ROS 2 Humble Hawksbill and Linux (Ubuntu 18.04)
  Implemented development processes for space flight software including version control with Git, automated unit testing and static analysis
- Robotics Engineer

BARRIOS TECHNOLOGY Nov 2021 – Aug 2022 • Supported NASA in developing test procedures for robotic systems on the International Space Station (ISS) on the JETS contract at Johnson Space Center

- **Automation Engineer** 
  - NABORS INDUSTRIES

April 2017 - Nov 2021

August 2022 – Jan 2023

- Designed fully automated robotic equipment with synchronous motion control for drilling operations using Siemens PLCs and Simotion motion controller
- Utilized ROS 1 Melodic Morena in a Linux (Ubuntu) environment to log data in an SQL Server database and produce optimization reports using the latest Python libraries
- Built a Python backend application with PostgreSQL database and HTML5/ JavaScript frontend to track assets during automated operations on a drilling rig
- Developed a vision system for detecting a key process event using classic vision and machine learning algorithms with OpenCV package for Python

## Automation Engineer

SUBMERSIBLE OIL-PUMP SERVICES

Aug 2016 - Apr 2017

- Built custom software for testing submersible oil pumps based on customer and API standards with intuitive touchscreen user interface
- Automated test systems to decrease testing time by utilizing PID control loops to achieve a desired flowrate by controlling the position of high-pressure valves
- Trained customers on equipment and collected user feedback for design improvements
- 11B (Infantryman), 21W (Carpentry & Masonry Specialist)
  - US ARMY

2001 - 2009

Rhode Island and Texas National Guard Long Range Surveillance (LRS) detachments

• As assistant squad leader led a team to complete constructions projects on time or early at Ballad Air Force Base in Iraq. Received Army Commendation Medal (ARCOM).

## EDUCATION

- Master of Computer Science RICE UNIVERSITY (4.0 GPA)

   Master of Business Administration (Leadership) UNIVERSITY OF HOUSTON DOWNTOWN (3.74 GPA)

   Jan 2019 - Aug 2022
- B.S. Controls and Instrumentation Engineering Technology
   UNIVERSITY OF HOUSTON DOWNTOWN (3.2 GPA)

Jan 2012 – May 2017

SKILLS

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Robotics	ROS1/2	OpenCV	Linux	Tensorflow	QT 6	Solidworks	Simulatior	CI/CD	
AWS Agil	e Versio	on Control	(Git)	SQL (PostgreSC	QL) PL	C Programmin	g Django	LabVIEW	
Python C/	C++ Java	a VB 6							
CERTIFICA	TIONS								

Certified Associate in Project Management (CAPM) Certified Cloud Practitioner Project Management Institute AWS